

### **Incremental Encoder**

# Series TRD-N

### **Operation Manual**

Thank you for purchasing this series TRD-N Incremental Encoder. Please read this Operation Manual carefully before applying this product.

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KEW-M8166D-E

### **Safety Consideration**

**\Warning** 

This indicates contents which can cause large accidents leading to loss of life or severe injury when the indication is disregarded and wrong handling is executed.

✓! Caution

This indicates contents which can cause injury or material damage when the indication is disregarded and wrong handling is executed

Explanation of the pictograms

This symbol indicates a general prohibition.

This symbol indicates a compulsory item or an instruction.

#### [Operating environment and conditions]

# Warning

Do not use in a combustible or explosive atmosphere Otherwise personal injury or fire may be caused.

Do not use this product for applications related to human safety. Use is assumed in an application where an accident or incorrect use will not immediately cause danger to humans.

### [Operating environment and conditions]

## **∕**!\Caution

Use and store the equipment within the scope of the Environment (vibrations, impact, temperature, humidity, etc.) specified in the

Otherwise fire or product damage may be caused.

Understand the product first before use it.

#### [Installation and wiring]

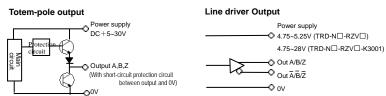
### Warning

Use only with the power supply voltage listed in the specifications. Otherwise fire, electric shock, or accidents may be caused.

Use only with the wiring and layout specified in the specifications. Otherwise fire, electric shock, or accidents may be caused.

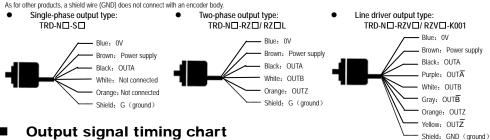
Do not apply any kind of stress to the wires. Otherwise electric shock or fire may be caused

#### **Output circuit**

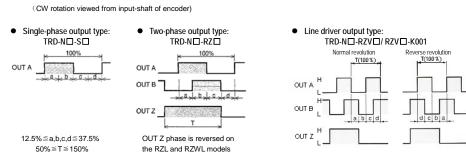


### Connection

More than 2501P/R, two-phase output type and Line driver output type, a shield wire (GND) is connected to the encoder's body.



### **Output signal timing chart**

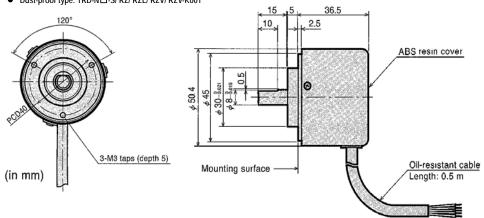


### **External dimensions**

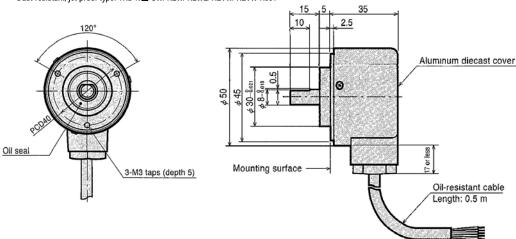
■ Mounting

(in mm)

● Dust-proof type: TRD-N□-S/ RZ/ RZL/ RZV/ RZV-K001



Dust-resistant, jet-proof type: TRD-N□-SW/ RZW/ RZWL/ RZVW/ RZVW-K001



# Mounting panel 3-M4 x 0.7 taps 120° Flange for servo mounting 120° (option)

The values in brackets are for the dust-resistant, jet-proof type

<u>39 (3</u>7.5)

## Electrical specifications

Type No.		TRD-N□-S□	$TRD-N\Box-RZ\Box/RZ\Box L$	$TRD-N\Box-RZV\Box$	TRD-N□-RZV□-K001**1	<ul><li>Bearing life</li></ul>	
Power supply	Operating voltage		DC4.75V~30V	DC4.75V~30V	DC4.75V~5.25V	DC4.75V~28V	ĝ10
	Allowable ripple		≤3%rms	≤3%rms	≤3%rms	≤3%rms	S10 Thrust lo
	Current consumption (no load)		≪40mA	≪60mA	≪60mA	≪40mA	5 10 20
Output waveform	Signal format		Single-phase output	Two-phase output with origin	Two-phase output with origin	Two-phase output with origin	0 ( ) ( ) ( ) ( ) ( ) ( ) ( ) ( ) ( ) (
	Max. response frequency		100kHz	100kHz	100kHz(200kHz:about 4096P/R)	100kHz	u 1
	Max. response rotating speed		(Maximum response frequency/Pulse)×60	(Maximum response frequency/Pulse)×60	(Maximum response frequency/Pulse)×60	(Maximum response frequency/Pulse)×60	
	Duty rate		50±25%	50±25%	50±25%	50±25%	
	Origin signal width		_	100±50%	100±50%	100±50%	20 40 60 80
	Rising/falling time × 2		≤3µs	≤3µs	≤2μs (	≤2µs	Radial k
Output	Output configuration		Totem-pole output	Totem-pole output	Line driver output (26C31 or equivalent)	Line driver output (OL7272 or equivalent)	
	Output logic		Positive logic (active high)	Positive logic (active high)	Positive logic (active high)	Positive logic (active high)	( ((\Phi)) ))
	Output current	Inflow	≤30mA	≤30mA			
		Outflow	≤10mA	≤10mA	_	_	
	Output voltage	"H"	≥[(Power supply voltage)— 2.5V]	≥[(Power supply voltage)— 2.5V]	≥2.5V	≥[(Power supply voltage) — 4V] (non-loaded)	● Origin positi
		"L"	≤0.4V	≤0.4V	≤0.5V	≤2V (non-loaded)	Adjustment is made by
	Load power supply voltage		≤DC35V	≤DC35V	-	_	mounting hole on the cable
	Short-circuit protection		(With short-circuit protection of	circuit between output and 0V)	_	_	side and the shaft notch ( down).

**Environmental requirements** 

### Mechanical specifications

	Starting torque	$\label{eq:max.0.003N • m (+20°C)} \mbox{(0.02N-m for the dust-resistant, jet-proof type.)}$	
	Shaft moment of inertia	2×10 <sup>-6</sup> kg • m <sup>2</sup>	
		Radial : 50N	
IV	Max. allowable shaft load	Thrust: 30N	
	Max. allowable speed	5000rpm (for the dust-resistant, jet-proof type: 3000rpm continuously and 5000rpm momentarily.)	
Cable	Material	Oil-resistant shielded cable 1	
	Nominal core cross section	0.3mm <sup>2</sup> (Line driver: 0.14mm <sup>2</sup> )	
	External diameter	Ф <b>6.0mm</b>	
Weight (With 0.5m cable.)		Approx. 150g	

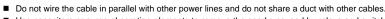
	Operation: −10∼+70°C				
Ambient temperature	Store: −25~+85°C				
Ambient humidity	35~85%RH (non-condensing)				
Withstand voltage	AC500V (50/60Hz) for 1 min	A power supply, signal Line and a cas			
Insulation resistance	50MΩ min.	Interval. Shield Line does not include			
Vibration resistance	10 $\sim$ 55Hz with 0.75mm amplitude $\divideontimes$ 2				
Shock resistance	~500P/R(metal slit),980m/s², 11ms ※3				
SHOCK TESISIATICE	600P/R~(glass slit),490m/s², 11ms × 3				
Protection	IP50: Dust-proof proofed				
construction	IP65: Dust-resistant, jet-proof type				

%1: TRD-N□-S□/RZ□: 5-core oil-resistant shielded cable TRD-N□- RZV□/ RZV□-K001: 8-core oil-resistant shielded cable

※2: Durable for 1h along 3 axes ※3: Applied 3 times 3 axes

- It is an examination condition, and it is not a thing to guarantee for consecutive us

### **Cautions for use**



- Use capacitors or surge absorption elements to remove the sparks caused by relays and switches in the control panel as fall
- Be sure to connect all wires properly, as wrong wiring can damage the internal circuitry.
- Erroneous pulses may be caused at the time of power ON and power OFF. After power ON, wait for at least 0.5 sec. before
- Do not disassemble the product. Do not expose the product for a long time to water, even if it is a dust-resistant, jet-proof type. Wipe off any water getting onto the product.
- As the rotary encoder is composed of precision parts, its function will be impaired when it is subjected to shocks. Use sufficient

