

# **Absolute Encoder** Series TRD-MA

## **Operation Manual**

Thank you for purchasing this series TRD-MA Absolute Encoders. Please read this Operation Manual carefully before applying this product.

This edition manual is applied to products that the batch number is 136B or later.

PLEASE KEEP MANUAL IN A SAFE PLACE!

#### **KOYO ELECTRONICS (WUXI) CO.,LTD.**

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### Safety Consideration

This indicates contents which can cause large accidents Warning leading to loss of life or severe injury when the indication is disregarded and wrong handling is executed.

This indicates contents which can cause injury or !\Caution material damage when the indication is disregarded and wrong handling is executed.

Explanation of the pictograms

This symbol indicates a general prohibition.

This symbol indicates a compulsory item or an instruction.

#### [Operating environment and conditions]

### Warning

- Do not use in a combustible or explosive atmosphere. Otherwise personal injury or fire may be caused.
- Do not use this product for applications related to human safety. Use is assumed in an application where an accident or incorrect use will not immediately cause danger to humans.

#### [Operating environment and conditions]

### **?**∖Caution

- Use and store the equipment within the scope of the environment (vibrations, impact, temperature, humidity etc.) specified in the specifications.
  - Otherwise fire or product damage may be caused.
- Understand the product first before use it.

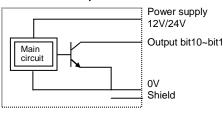
#### [Installation and wiring ]

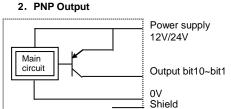
### Warning

- Use only with the power supply voltage listed in the specifications. Otherwise fire, electric shock, or accidents may be caused.
- Use only with the wiring and layout specified in the specifications. Otherwise fire, electric shock, or accidents may be caused.
- Do not apply any kind of stress to the wires. Otherwise electric shock or fire may be caused.

### **Output circuit**

1. NPN Output





### **Mechanical specifications**

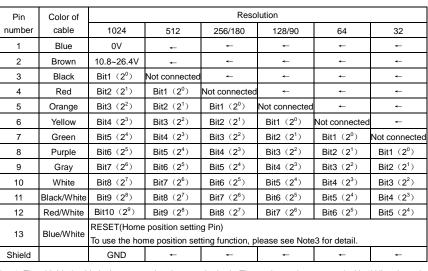
Starting torque		Max. 0.01N • m (+20°C)	
Shaft moment of inertia		$0.3\times10^{-6}\mathrm{kg}\bulletm^2$	
Max. allowable	Radial	20N	
shaft load	Thrust	30N	
Max. allowa	ble speed	3000rpm	
	Material	Oil-resistant PVC(with shielded cable)	
Cable	Nominal core cross section	0.14mm <sup>2</sup>	
	External diameter	Approx. 7.0mm	
Wei	ght	Approx.150g(cable length 2m)	

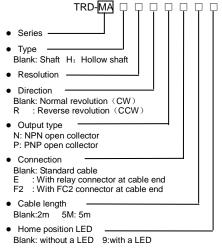
### **Environmental requirements**

Ambient temperature	Operation temperature: −20~+75°C	
	Storage temperature: −25~+85°C	
Ambient humidity	35~85%RH (non-condensing)	
Withstand voltage	AC500V 1minute	
Insulation resistance	e 10MΩ min.	
Vibration resistance	Durable for 1h along 3 axes at 10 to 55Hz with 0.75mm amplitude:	
Shock resistance	11ms with 490m/s <sup>2</sup> applied 3 times 3 axes	
Protection construction	Dust proofed:IP50 (magnetic permeability cast-iron casing	
Withstand voltage Insulation resistance Vibration resistance Shock resistance	AC500V 1minute $10M\Omega  \text{min.}$ Durable for 1h along 3 axes at 10 to 55Hz with 0.75mm amplitud $11\text{ms with }490\text{m/s}^2 \text{ applied 3 times 3 axes}$	

#### Connection

## Composition of model number





#### **Electrical specifications**

Type No.			TRD-MA		
	Operating voltage		10.8V~26.4V DC		
Power supply	Allowable ripple		3%rms Max.		
supply	Current consumption		50mA Max. (without load)		
	Signal format		Binary gray code		
	Max. response frequency		30kHz		
Output waveform	Electric Max. allowable speed		(Maximum response frequency/Pulse)x60 (The encoder can not respond to revolution faster than the electric maximum allowable speed.)		
	Precision		(360/resolution) °		
	Direction		Output code increments in positive direction of CW, Output code decrements in negative direction of CCW ( CW means clockwise revolution viewed from the shaft.)		
	Rising/falling time		2µs Max.		
	Output type		open collector output(NPN)	open collector output(PNP)	
	Outp	ut logic	Negative logic (low active)	Positive logic (high active)	
Output	Residual voltage	lo=16mA	0.4V Max.		
		lo=32mA	1.5V Max.		
	Inflow current		32mA Max.		
	Load power supply voltage		DC30V Max.		

Note1: The shielded cable isn't connected to the encoder body. The enclosure is connected with 0V line through a capacitance.

Note2: The shielded cable can not be connected with the internal signal line.

Note3: The Pin 13(RESET) is used to set the home position. Two method shows followed:

- 1. Used a mechanical switch or a relay to connect the RESET terminal with the 0V terminal. When the switch or the relay turn OFF, the current position set to the home position. Otherwise, it needs to keep the switch or the relay ON. (or short the RESET terminal and the 0V terminal.)
- 2. Connect the voltage signal to the RESET terminal and the 0V terminal. The current position will be set to the home position as the voltage between DC5V to DC24V range. Otherwise, it needs to keep the voltage in range of 0 to 0.8VDC.

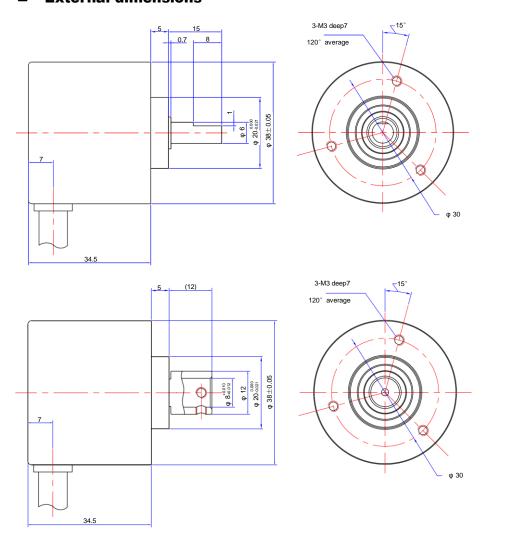
After finished the setting, the encoder output code will reset to '0', which means the current position is the home position. In the meantime the home position LED will be lighting(for type with home position LED). If you needn't the home position setting function, you should short the RESET terminal and the 0V terminal when you use the encoder.

The timing chart of RESET signal for home position setting is showed left:

Ton: denotes effective time of control signal, it means the minimum time of the switch or the relay turn OFF (or means the time of the voltage is kept to DC5V to DC24V range among the 0V terminal and the RESET terminal). Ton > 120ms

Tp: denotes the time of Reset Process after received the effective RESET signal.

### **External dimensions**



### **Cautions for use**

- Do not wire the cable in parallel with other power lines and do not share a duct with other cables.
- Use capacitors or surge absorption elements to remove the sparks caused by relays and switches in the control panel as far as possible.
- Be sure to connect all wires properly, as wrong wiring can damage the internal circuitry.
- Use a specified coupling for connecting the encoder shaft and the shaft of a machine to be controlled. Do not squeeze the shaft into the coupling.
- The service life of the bearing is largely affected by the amount of load to the shaft. Try to reduce the load as much as possible.
- Do not disassemble the product.
- As the rotary encoder is composed of precision parts, its function will be impaired when it is subjected to shocks. Use sufficient care for handling and mounting.

